

Autoclave Automation Using PLC & SCADA

¹lipsa Behera, ²sonam Swarupa

Gandhi Institute of Excellent Technocrats, Bhubaneswar, India

Indus College of Engineering, Bhubaneswar, Odisha, India

ABSTRACT-

Automation generally refers to the science and technology of process control and includes the control of chemical and petrochemical plants, Oil refineries, iron and steel plant, Power plants, cement mills, Paper pulp and paper mills water and waste water treatment plants and many like all this. The basic objective of automation is identifying the information flow and manipulates the material and energy flow as given process in a desired way. PLC & SCADA plays an important role in automating industrial system.

This work shows how automation is carried & implemented with software interface, PLC & Micro-SCADA in C.G. Ltd. Nashik, Maharashtra, India for CVT autoclave. The whole process is of 121 hrs consisting of number of cycles, which is automated using PLC & SCADA for all process parameters.

Key Words:- PLC, SCADA, Automation, Case Study - Autoclave Automation.

INTRODUCTION

PLC:- (PROGRAMMABLE LOGIC CONTROLLERS)

Automation of many different processes, such as controlling machines or factory assembly lines, is done through the use of small computers called as **Programmable Logic Controller (PLC)**. This is actually a control device that consists of a programmable microprocessor, and is programmed using a specialized computer language.

Today, programmable logic controllers deliver a wide range of functionality, including basic relay control, motion control, process control, and complex networking, as well as being used in Supervisory Control and Data Acquisition Systems and Distributed Control Systems.

1. PLC PROGRAMMING

Previously programmable logic controller were programmed in ladder logic, which is similar to a schematic of relay logic. Modern programmable logic controller is usually programmed in any one of several languages, ranging from ladder logic to Basic or C. Typically the program is written in a development environment on a personal computer, and then is downloaded onto the programmable logic controller directly through a cable connection.

Recently, the International standard IEC 61131-3 has become popular currently defines 5 programming languages for programmable control systems:

FBD (Function Block Diagram), LD (Ladder Diagram),

ST (Structured Text, Pascal type lang.) IL (Instruction List)

SFC (Sequential function chart)

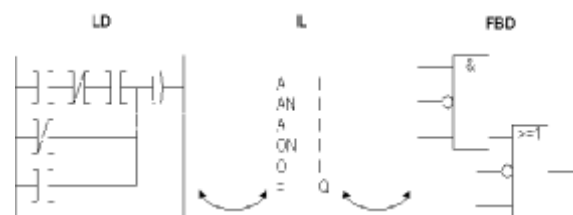


Fig No. 1 PLC block Diagram

PLC Operation & Working Principle

A PLC works by continually scanning a program. The scan cycle consists of three important steps. There are typically more than three but we focus on the important parts.

- **Check Input Status:** First the PLC takes a look at each input to determine if it is on or off. In other words, is the sensor connected to the first input? How about the second input? And so on it checks all the connected inputs. It records this data into its memory to be used during the next step.
- **Execute Program:** Next the PLC executes your program, one instruction at a time.
- **Update output Status:** Finally the PLC updates the status of the outputs based on which inputs were on during the first step and the results of executing your program during the second step.

PLC Selection

Some of the key factors for the selection of PLC

- Number of I/O required
- Expandability
- Cost
- Serviceability/Support
- Flexibility

Ordering Specifications

Power Supply: AC/DC, 220V AC/24 V DC. Configuration: Total Input and Output Details- Digital and Analog.

User Interface

PLCs may need to interact with people for the purpose of configuration, alarm reporting or everyday control. A Human-Machine interface (HMI) is employed for this purpose. A simple system may use buttons and lights to interact with the user. Text displays are available as well as graphical touchscreens. Most modern PLCs can communicate over a network to some other system, such as a computer running a SCADA system.

2. S.C.A.D.A

3.1 S.C.A.D.A.-(SUPERVISORY CONTROL AND DATA ACQUISITION) can mean many things to many

etc. As incoming data changes the screen is updated. Figure shows the examples of inputs from the MTU and field devices.

Remote Terminal Unit

Remote terminal units gather information from their remote site from various input devices, like valves, pumps, alarms, sensors, meters, etc. Essentially, data is either analog (real numbers), digital (on/off), or pulsed data (e.g., counting revolutions of meters). Many remote terminal units hold the information gathered in their memory and wait for a request from the MTU to transmit the data. Other more sophisticated remote terminal units have microcomputers and PLC that perform direct control over a remote site without the direction of the MTU. The RTU central processing unit receives a binary data stream in accordance with the communication protocol. Protocols can be open, like Transmission Control Protocol and Internet Protocol (TCP/IP) or proprietary. Figure shows an example of output of the RTU to MTU and field

people. The acquisition of data, the processing of that data for use by the operator, and operator control of remote devices are the fundamental building blocks upon which all modern utility control systems are based. The system to accomplish these functions is known as a SCADA system. As the name indicates, it is not a full control system, but rather focuses on the supervisory level. As such, it is a purely software package that is positioned on top of hardware to which it is interfaced, in general via Programmable Logic Controllers, or other commercial hardware modules.

Inputs from MTU

- ☐ Discrete Control order
- ☐ Analog setting Instructions
- ☐ Stepping Motor Pulses
- ☐ Order store response

Inputs from field devices

- Field Analog Signal
- Alarms switch Signal

RTU

Output to field devices

- Contact Closure or 0-24V controls
- Analog control
- Pulse Train stepping Motor Control
- Serial Message to field Equipment

Output to MTU

- Field Analog Signal
- Alarms
- Equipment status
- Totaled Meters signals

Basic SCADA Elements

There are four major elements to a SCADA system, master terminal unit (MTU), communications, and remote terminal unit (RTU). The operator exercises

- Equipment status signal
- Pulse Meter Signal
- Serial Message from field
- Equipment Message

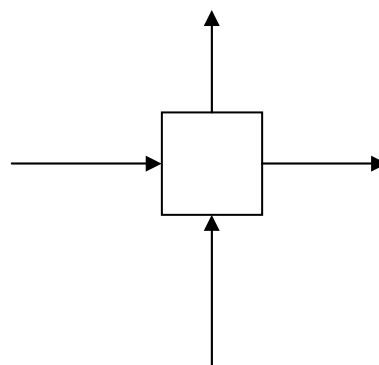
control through information that is depicted on a video display unit (VDU). Input to the system normally initiates from the operator via the master terminal unit's keyboard. The MTU monitors information from remote sites and displays information for the operator. The relationship between MTU and RTU is analogous to master and slave. SCADA systems are capable of communicating using a wide variety of media such as fiber optics, dial-up, or dedicated voice grade telephoned lines, or radio.

Master Terminal Unit

At the heart of the system is the master terminal unit (MTU). The master terminal unit initiates all communications, gathers data, stores information, sends information to other systems, and interfaces with operators. The major difference between the MTU and RTU is that the MTU initiates virtually all communications by its programming and people. Almost all communication is initiated by the MTU. The MTU also communicates with other peripheral devices in the facility like monitors, printers or other information systems. The primary interface to the operator is the monitor that portrays a representation of valves, pumps,

Fig.No.2:- Inputs & Outputs for RTU

The data acquisition part of SCADA is getting more PC-Based than stand-alone hardware. Many of today's RTU is either a Personal Computer or a Programmable Logic Controller (PLC)



Why SCADA System & Functions

Some basic needs are listed below

- **Save Time:** The time taken to travel remote sites together information or issue controls, to sift through manually entered data, write out a report or perform any of the functions that a SCADA system does as a matter of course is considerable. Time saving benefits go far beyond the man hours saved - timeliness of alarms, actions, control have high monetary value as well.
- **Avoid Trouble:** A SCADA system's primary purpose is to give advance warning of trouble. Hence action can be taken before it swallows the whole system and creates problem.
- **Achieve Systemwide Processes:** SCADA systems afford the user an opportunity to monitor and control processes that take place over a wide geographical area. e.g., A sewage treatment plant or energy management system. These applications can cause considerable financial savings in running cost and capital cost which can pay for the cost of SCADA in itself.
- **Save Manpower:** Before SCADA systems were implemented; remote sites such as substations and pumping stations were either manned or inspected frequently. The need for this was eliminated or greatly reduced by the implementation of wide area SCADA. This was the primary economic driver for SCADA system implementation in the first great wave of comprehensive systems in the 1970's and 1980's.

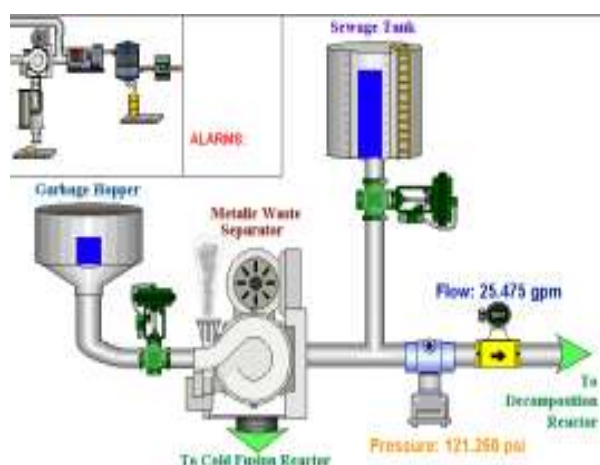


Fig.No.4:-Graphical Screen Of Process

SCADA Functions

- **Access Control:** - Users are allocated to groups, which have defined read/write access privileges to the process parameters in the system and often also to specific product functionality.
- **MMI:** - The product supports multiple screens, which can contain combinations of synoptic diagrams and text. They also support the concept of a "generic" graphical object with links to process variables. These objects can be "dragged and dropped" from a library and included into a synoptic diagram.

Most of the SCADA products that were evaluated decompose the process in "atomic" parameters (e.g. a power supply current, its maximum value, its on/off status, etc.) to which a Tag-name is associated. The Tag-names used to link graphical objects to devices can be edited as required. The products include a library of standard graphical symbols, many of which would however not be applicable to the type of applications encountered in the experimental physics community.

Standard window editing facilities are provided: zooming, re-sizing, scrolling... On-line configuration and customization of the MMI is possible for users with the appropriate privileges. Links can be created between display pages to navigate from one view to another.

- **Trending:-**

The products all provide trending facilities and one can summarize the common capabilities as follows:

- The parameters to be trended in a specific chart can be predefined or defined on-line
- A chart may contain more than 8 trended parameters or pens and an unlimited number of charts can be displayed (restricted only by the readability)
- Real-time and historical trending are possible, although generally not in the same chart
- Historical trending is possible for any archived parameter
- Zooming and scrolling functions are provided
- Parameter values at the cursor position can be displayed

The trending feature is either provided as a separate module or as a graphical object (ActiveX), which can then be embedded into a synoptic display. XY and other statistical analysis plots are generally not provided.

- **Alarm Handling :-** Alarm handling is based on limit and status checking and performed in the data servers. More complicated expressions (using arithmetic or logical expressions) can be developed by creating derived parameters on which status or limit checking is then performed. The alarms are logically handled centrally, i.e., the information only exists in one place and all users see the same status (e.g., the acknowledgement), and multiple alarm priority levels (in general many more than 3 such levels) are supported.

It is generally possible to group alarms and to handle these as an entity (typically filtering on group or acknowledgement of all alarms in a group). Furthermore, it is possible to suppress alarms either individually or as a complete group. The filtering of alarms seen on the alarm page or when viewing the alarm log is also possible at least on priority, time and group. However, relationships between alarms cannot generally be defined in a straightforward manner. E-mails can be generated or predefined actions automatically executed in response to alarm conditions.

- **Logging/Archiving:-** The terms logging and archiving are often used to describe the same facility. However, logging can be thought of as medium-term storage of data on disk, whereas archiving is long-term storage of data either on disk or on another permanent storage medium. Logging is typically performed on a cyclic basis, i.e., once a certain file size, time period or number of points is reached the data is overwritten. Logging of data can be performed at a set frequency, or only initiated if the value changes or when a specific predefined event occurs. Logged data can be transferred to an archive once the log is full. The logged data is time-stamped and can be filtered when viewed by a user. The logging of user actions is in general performed together with either a user ID or station ID. There is often also a VCR facility to play back archived data.

- **Report Generation:-** One can produce reports using SQL type queries to the archive, RTDB or logs. Although it is sometimes possible to embed EXCEL charts in the report, a "cut and paste" capability is in general not provided. Facilities exist to be able to automatically generate, print and archive reports.

- **Automation:-** The majority of the products allow actions to be automatically triggered by events. A scripting language provided by the SCADA products allows these actions to be defined. In general, one can load a particular display, send an Email, and run a user-defined application or script and write to the RTDB. The concept of recipes is supported, whereby a particular system configuration can be saved to a file and then re-loaded at a later date.

Sequencing is also supported whereby, as the name indicates, it is possible to execute a more complex sequence of actions on one or more devices. Sequences may also react to external events.

3. CONNECTIONS & PROTOCOLS

As mentioned earlier that PLC is used frequently in a SCADA system as the RTU. We need to throw some light on the communication between the SCADA Computer and the PLC. There are several different types of connections between the SCADA computers and PLCs. For example, RS232, RS422, RS485, and Ethernet. Note that these are only the electrical connection and do not specify the protocol or language used on the connection. We can call this as the Hardware protocol. Each PLC manufacturer has their own protocol or language that the PLC speaks. For example, Allen-Bradley (Rockwell) PLCs talk DF1, Data Highway 485 (DH485), Data Highway (DH), Data Highway+ (DH+), Remote I/O (RIO), DeviceNet, ControlNet, and a few others. Talk about an identity complex! Modicon PLCs speak Modbus, Modbus Plus, and now Modbus TCP/IP (Modbus over Ethernet). Automation Direct PLCs speak Directed and K-sequence protocols while some of their PLCs still communicate using their old protocols. The old GE PLC protocol was CCMB but they now use SNP and variants such as SNPX. Siemens PLCs work mainly with the Profibus protocol which is considered more of an open, rather than proprietary, protocol.

The most common "standard" protocols we see are DF1, Modbus, and Profibus. DF1 and Modbus are popular since they have been around longer than many of the people using them. Profibus is popular because, in our humble opinion, combines the best of simplicity (daisy chain, twisted pair), industrial ruggedness

(RS485), speed (12 MBaud), adaptability (you can select from many different speeds), scalability (from simple COM port up to communications controllers), and function (most automation devices can talk Profibus). Typically all PLC manufacturers will have a PLC module that will talk these protocols.

Now that Ethernet is becoming the "most hyped" capability in automation there are several protocols over Ethernet. But remember -- just because an Allen-Bradley and a Siemens PLCs are both put on the same Ethernet cable -- they cannot talk to each other because they do not use the same protocol.

4.1 SCADA CONFIGURATION

Configuration in SCADA should be done sequentially only. This is having following sequence.

1. Protocol Configuration
2. Port Configuration.
3. Device Configuration
4. Tag Configuration
5. Role Configuration

4.2 APPLICATION OF SCADA

- Electric Utility
- Water/Waste Water Utilities
- Oil & Gas Transmission & Distribution
- Communication Networks
- Industrial Process Control
- Etc.

5. CASE STUDY – AUTOCLAVE AUTOMATION Company: - Crompton Greaves Ltd. , Nashik

Address:- G.G.Ltd.Ambad,Nashik,Maharashtra,India-422004,

Contact No.:- Mr. Shirde M.M. (+91-09422270801) Products:- C.B.s, RELAYS, CT'S, PT'S, CVT's

Process Of Study & Design:- Autoclave Automation

A case study of "AUTOCLAVE AUTOMATION" at Crompton Greaves, Nashik is considered. Demand for Capacitive Voltage Transformer (CVT) has risen from past few years, because of features such as metering, protection & Carrier communication all being present in one single product, also it is repairable in case of failure. Considering the entire above thing CG wanted to increase their rate of CVT production by reduction of process time & manpower with enhanced quality. Since Autoclave process is one of the major processes in the CVT product cycle and also takes 5 & ½ days, the need for its time optimization was faced, which was achievable through its automation.

Specification Of CVT Autoclaves

1. Size – 1400mm ID X 2000mm useful Height
2. Purpose Processing of Capacitor Tags & Electromagnetic Units
3. Heating System – Thermic Fluid
4. Processing Cycle has follows
5. Hydraulic Lifting Cover for Autoclave
6. Quantity Req'd. = 03 Nos
7. PC / PLC with SCADA System common for all 03 Autoclaves & provision for another 03 Autoclaves on the same PC.
8. During FINE VACUUM Stage we must get 50 microns Vacuum on Pirani Gauge in first 24 Hours for both type of cycles.
9. Oil Heat exchanger with flow meter for temp. Controlled oil flow rate. (Max 200 Lts/hr) at 50 deg. Cent.
10. Automatic vacuum control between 100 to 200 microns during oil impregnation state
11. Control through PLC & monitoring through SCADA system.
12. Activated alumina for vacuum breaking.

Process Description

As mentioned in specification the process cycle consists of alternate cycles of Air Heating & Rough Vacuum followed by Fine Vacuum & impregnation cycles. Since capacitive voltage Transformer consists of mix dielectric, there is the need of heating the product to remove

moisture from the paper in the form of vapors. This is done in air heating cycle. The moisture in the form of vapors is sucked from the autoclave in the rough vacuum cycle. The Air Heating & rough vacuum cycle are alternatively till a temp. Of 115 deg. Cels. & Vacuum of 15 mbar is achieved. The duration for the cycles is mentioned in the table. After this Fine Vacuum Heating is carried out in which Vacuum of 50 microns is achieved, then the Fine Vacuum Cooling in which the temp. is brought to 60 deg. Cels. & the Vacuum levels of 100 microns are achieved. The end cycle is Oil Impregnation, which is carried out under vacuum of greater than 100 microns.

Device Used for Process:-

1. Thermic Fluid Pump – used in heating system
2. Air circulation Fan – One ON during Air Heating
3. Roots Vacuum Pump – One ON during Fine Vacuum
4. Vacuum Pump 1 (Single Stage) – One ON during Rough Vacuum
5. Vacuum Pump 2 (Double Stage) – One ON during Fine Vacuum
6. Hydro Power Pack – for Automatic Door Opening/Closing
7. Three RTD's – Temp. Sensing
8. Pirani Vacuum Gauge – Vacuum measurement
9. Electrically operated Solenoid Valves
10. Light Flasher
11. Liquid Level Sensors
12. PLC & PC

Designed Logic for system

Logic of only one cycle is mentioned & others are on similar basis. Logic is prepared considering the different interlocking that needs to be satisfied for the output to get activate.

Before start of the cycle the door should be closed that is the NO s/w of the door limit need to be closed. This act as one of the digital I/P to the PLC.

5.4.1 AH1:-

- Open Thermic Fluid Line Valves
- Start Air circulation Fan
- Vacuum Valves should be Closed
- Start Timer at the cycle start (The Set Value for the timer is 18 Hrs.)

5.4.2 Switching from AH 1 to RV1 conditions-

- Job Temp. 105 deg. Cels. & AH1 Time completed
- Chilling Pump ON

TABLE NO.1 VACUUM DETAILS

Stage	Temp Deg. Celc	Vacuum	Duration Hrs. for Capacitor Cycle	Duration Hrs. for EMU Cycle
AH 1	105	-	18	08
RV1	105	35mbar	06	04
AH 2	110	-	04	-
RV2	115	25mbar	12	-
AH 3	115	-	-	-
RV3	115	15mbar	-	-
FVH	115	50 microns	60	12
FVC	60	100 microns	25	12
OI	60	100–200 microns	06	06

RV – Rough Vacuum FVC – Fine Vacuum Cooling OI – Oil Impregnation FVH – Fine Vacuum Heating AH – Air Heating

BasicDesignSoftware: -Complicity

FrontEndDesign:-VisualBasic,VC++.BackEnd Design:-Oracle, SQL

ReportGeneration:-Excel,Access.

1. FrontMonitoringScreenSCADAWorkbenchview

2. AutoclaveControlScreen
3. FrontEndOfA-9AutoclaveMenu

- ## 5. A-9VacuumSystem

- ## 6. HeatingSystem

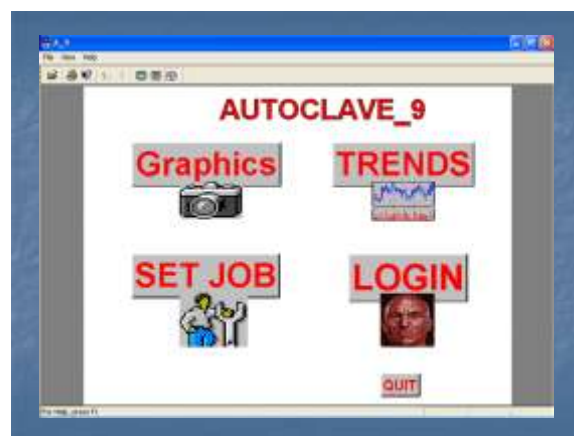
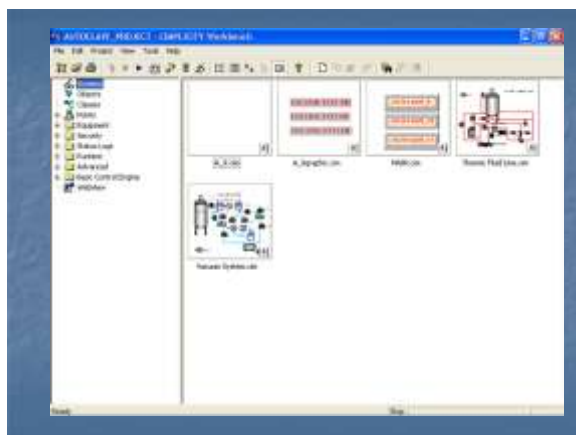


Fig.No.7:-FrontEndOfA-9 AutoclaveMenu



CONCLUSION

The case study of Autoclave Automation is described briefly because of the space constraint. The SCADA system for the case is design as per the customer requirement. Because of this automation both the product as well as process time is optimized. This work shows how automation is carried & implemented with software interface, PLC & Micro-SCADA in C.G.Ltd. Nashik, Maharashtra, India for CVT autoclave. The whole process is of 121 hrs. Consisting of number of cycles, which is automated using PLC & SCADA for all process parameters.

REFERENCES

- [1] Sonawane Y.D., Patil P.M., Thorat S.C., Landeg S.C., CISCON-2005, Manipal, Karnataka, India, 95-101, 11-12 Nov. 2005, "Advance Techniques Of Energy Conservation & Management"
- [2] Lester Abbey, SCADA conference 2003. 75 80 "Evolution of SCADA systems"
- [3] Dennis J. Gausheel & Henry T. Darlington, IEEE paper. 25-31 "Supervisory Control & Data Acquisition"
- [4] Duong trung 1995 IEEE paper, 120-125 "The Design of next Generation SCADA systems"
- [5] Abhijit Hazara, Kaushik Ghosh, "Embedded Micro SCADA", in ICSCI-06 Int. Conf., Jan. 2006, pp. 163-168.
- [6] Samuel C. Scacca, "Advanced SCADA Concept" IEEE transaction, 1995, 95-99.
- [7] Armin Biere, "Resolve and Expand", Proc. of SAT 2004, 2004.
- [8] Cimplicity, "SCADA", ABB manual, 1986.
- [9] P. G. Paulin, C. Liem, M. Cornero, F. Nacabal, and G. Goossens, "Embedded software in real-time signal processing systems: application and architecture trends," Proc. IEEE, vol. 85, no. 3, pp. 419-435, Mar. 1997.